Explicit inverses of some tridiagonal matrices

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Received 28 April 1999; accepted 26 June 2000

Submitted by G. Heinig

Abstract

We give explicit inverses of tridiagonal 2-Toeplitz and 3-Toeplitz matrices which generalize some well-known results concerning the inverse of a tridiagonal Toeplitz matrix. © 2001 Elsevier Science Inc. All rights reserved.

AMS classification: 33C45; 42C05

Keywords: Invertibility of matrices; r-Toeplitz matrices; Orthogonal polynomials

1. Introduction

In recent years the invertibility of nonsingular tridiagonal or block tridiagonal matrices has been quite investigated in different fields of applied linear algebra (for historical notes see [8]). Several numerical methods, more or less efficient, have risen in order to give expressions of the entries of the inverse of this kind of matrices. Though, explicit inverses are known only in a few cases, in particular when the tridiagonal matrix is symmetric with constant diagonals and subject to some restrictions (cf. [3,8,10]). Furthermore, Lewis [5] gave a different way to compute other explicit inverses of nonsymmetric tridiagonals matrices.

In [1], Gover defines a tridiagonal 2-Toeplitz matrix of order $n$, as a matrix $A = (a_{ij})$, where $a_{ij} = 0$ if $|i - j| > 1$ and $a_{ij} = a_{kl}$ if $(i, j) \equiv (k, l) \mod 2$, i.e.,
Similarly, a tridiagonal 3-Toeplitz matrix \((n \times n)\) is of the form
\[
B = \begin{pmatrix}
  a_1 & b_1 & c_1 & 0 \\
  c_1 & a_2 & b_2 & 0 \\
  c_2 & a_3 & b_3 & 0 \\
  \vdots & \vdots & \vdots & \ddots \\
  c_n & a_1 & \cdots & 0
\end{pmatrix}_{n \times n}.
\]

Making use of the theory of orthogonal polynomials, we will give the explicit inverse of tridiagonal 2-Toeplitz and 3-Toeplitz matrices, based on recent results from [1,6,7]. As a corollary, we will obtain the explicit inverse of a tridiagonal Toeplitz matrix, i.e., a tridiagonal matrix with constant diagonals (not necessarily symmetric). Different proofs of the results by Kamps [3,4] involving the sum of all the entries of the inverse can be simplified.

Throughout this paper, it is assumed that all the matrices are invertible.

2. Inverse of a tridiagonal matrix

Let \(T\) be an \(n \times n\) real nonsingular tridiagonal matrix
\[
T = \begin{pmatrix}
  a_1 & b_1 & 0 \\
  c_1 & a_2 & b_2 \\
  c_2 & \ddots & \ddots \\
  \vdots & \ddots & \ddots \\
  c_{n-1} & \cdots & a_n
\end{pmatrix}.
\]
Denote \(T^{-1} = (a_{ij})\). In [5] Lewis proved the following result.

Lemma 2.1. Let \(T\) be the matrix (3) and assume that \(b_\ell \neq 0\) for \(\ell = 1, \ldots, n - 1\). Then
\[
\alpha_{ji} = \gamma_{ij} a_{ij} \quad \text{when} \quad i < j,
\]
where
\[ \gamma_{ij} = \prod_{\ell=i}^{j-1} \frac{c_\ell}{b_\ell}. \]

Of course this reduces to \( \gamma_{ij} = \gamma_{ji} \), when \( T \) is symmetric.

Using this lemma, one can prove that there exist two finite sequences \( \{u_i\} \) and \( \{v_i\} \) \( (i = 1, \ldots, n - 1) \) such that
\[
T^{-1} = \begin{pmatrix}
  u_1 v_1 & u_1 v_2 & u_1 v_3 & \cdots & u_1 v_n \\
  \gamma_{12} u_1 v_2 & u_2 v_2 & u_2 v_3 & \cdots & u_2 v_n \\
  \gamma_{13} u_1 v_3 & \gamma_{23} u_2 v_3 & u_3 v_3 & \cdots & u_3 v_n \\
  \vdots & \vdots & \vdots & \ddots & \vdots \\
  \gamma_{1,n-1} u_1 v_{n-1} & \gamma_{2,n-1} u_2 v_{n-1} & \gamma_{3,n-1} u_3 v_{n-1} & \cdots & u_n v_n
\end{pmatrix}.
\]

(4)

Since \( \{u_i\} \) and \( \{v_i\} \) are only defined up to a multiplicative constant, we make \( u_1 = 1 \).

The following result shows how to compute \( \{u_i\} \) and \( \{v_i\} \). The determination of these sequences is very similar to the particular case studied in [8], where the reader may check for details.

Lemma 2.2. (i) The \( \{v_i\} \) \( (i = 1, \ldots, n - 1) \) can be computed from
\[
v_1 = \frac{1}{d_1}, \quad v_k = -\frac{b_{k-1}}{d_k} v_{k-1}, \quad k = 2, \ldots, n,
\]
where
\[
d_n = a_n, \quad d_i = a_i - b_i c_i d_{i+1}, \quad i = n - 1, \ldots, 1.
\]

(ii) The \( \{u_i\} \) \( (i = 1, \ldots, n - 1) \) can be computed from
\[
u_n = \frac{1}{\delta_n v_n}, \quad u_k = -\frac{b_k}{\delta_k} u_{k+1}, \quad k = n - 1, \ldots, 1,
\]
where
\[
\delta_1 = a_1, \quad \delta_i = a_i - b_{i-1} c_{i-1} \delta_{i-1}, \quad i = 2, \ldots, n - 1.
\]

Notice that for centro-symmetric matrices, i.e., \( a_{ij} = a_{n+1-i,n+1-j} \), we have
\[
v_i = u_{n+1-i}.
\]

The following proposition is known in the literature. We give a proof based on the lecture of [8].

Theorem 2.1. Let \( T \) be the \( n \times n \) tridiagonal matrix defined in (3) and assume that \( b_\ell \neq 0 \) for \( \ell = 1, \ldots, n - 1 \). Then
\[(T^{-1})_{ij} = \begin{cases} \frac{(-1)^{i+j} b_i \cdots b_{j-1} d_{j+1} \cdots d_n}{\delta_i \cdots \delta_n} & \text{if } i \leq j, \\ \frac{(-1)^{i+j} c_j \cdots c_{j-1} d_{i+1} \cdots d_n}{\delta_j \cdots \delta_n} & \text{if } i > j \end{cases} \]

(with the convention that empty product equals 1).

**Proof.** Let us assume that \( i \neq j. \) Then
\[
(T^{-1})_{ij} = u_i v_j = (-1)^{n-1} \frac{b_1 \cdots b_{n-1}}{\delta_1 \cdots \delta_n} v_n \]

But
\[
v_n = (-1)^{n-1} \frac{b_1 \cdots b_{n-1}}{d_1 \cdots d_n}.
\]

Therefore
\[
(T^{-1})_{ij} = (-1)^{n-1} \frac{b_1 \cdots b_{n-1}}{\delta_i \cdots \delta_n} v_n = (-1)^{j-1} \frac{b_1 \cdots b_{j-1}}{d_1 \cdots d_j}.
\]

If we set
\[
\delta_i = \frac{\theta_i}{\theta_{i-1}}, \quad \theta_0 = 1, \quad \theta_1 = a_1,
\]
we get the recurrence relation
\[
\theta_i = a_i \theta_{i-1} - b_{i-1} c_{i-1} \theta_{i-2};
\]
and if we now put
\[
d_i = \frac{\phi_i}{\phi_{i+1}}, \quad \phi_{n+1} = 1, \quad \phi_n = a_n,
\]
we get the recurrence relation
\[
\phi_i = a_i \phi_{i+1} - b_i c_i \phi_{i+2}.
\]

As a consequence, we will achieve
\[
(T^{-1})_{ij} = \begin{cases} \frac{(-1)^{i+j} b_i \cdots b_{j-1} \theta_i \phi_{j+1}}{\theta_n} & \text{if } i \leq j, \\ \frac{(-1)^{i+j} c_j \cdots c_{j-1} \theta_j \phi_{i+1}}{\theta_n} & \text{if } i > j \end{cases}
\]

These are the general relations given by Usmani [9], which we will use throughout this paper. Notice that
\[
\theta_n = \delta_1 \cdots \delta_n = \det T.
\]
3. Chebyshev polynomials of the second kind

In the next it is useful to consider the set of polynomials \( \{U_n\}_{n \geq 0} \), such that each \( U_n \) is of degree exactly \( n \), satisfying the recurrence relation
\[
U_{n+1}(x) = 2xU_n(x) - U_{n-1}(x), \quad n \geq 1
\]
with initial conditions
\[
U_0 = 1 \quad \text{and} \quad U_1 = 2x.
\]
These polynomials are called Chebyshev polynomials of the second kind and they have the form
\[
U_n(x) = \frac{\sin((n+1)\theta)}{\sin \theta}, \quad \text{where} \quad \cos \theta = x,
\]
when \( |x| < 1 \). When \( |x| > 1 \), they have the form
\[
U_n(x) = \frac{\sinh((n+1)\theta)}{\sinh \theta}, \quad \text{where} \quad \cosh \theta = x.
\]
In particular
\[
U_n(\pm 1) = (\pm 1)^n(n + 1).
\]
In any case, if \( |x| \neq 1 \), then
\[
U_n(x) = \frac{r_+^{n+1} - r_-^{n+1}}{r_+ - r_-},
\]
where
\[
r_{\pm} = x \pm \sqrt{x^2 - 1}
\]
are the two solutions of the quadratic equation \( r^2 - 2xr + 1 = 0 \).

The following proposition is a slight extension of Lemma 2.5 of Meurant [8].

**Lemma 3.1.** Fix a positive integer number \( n \) and let \( a \) and \( b \) be nonzero real numbers such that \( U_i(a/2b) \neq 0 \) for all \( i = 1, 2, \ldots, n \). Consider the recurrence relation
\[
\alpha_1 = a, \quad \alpha_i = a - \frac{b^2}{\alpha_{i-1}}, \quad i = 2, \ldots, n.
\]
Under these conditions, if \( a = \pm 2b \), then
\[
\alpha_i = \pm \frac{b(i + 1)}{i}.
\]
Otherwise
\[
\alpha_i = b\frac{r_+^{i+1} - r_-^{i+1}}{r_+^i - r_-^i}.
\]
where
\[ r_{\pm} = \frac{a \pm \sqrt{a^2 - 4b^2}}{2b} \]
are the two solutions of the quadratic equation \( r^2 - (a/b)r + 1 = 0 \).

**Proof.** Let us assume that \( a \neq \pm 2b \) (otherwise it is trivial) and set \( \alpha_i = \beta_i/\beta_{i-1} \).

Then
\[ \beta_i - a\beta_{i-1} + b^2\beta_{i-2} = 0, \quad \beta_0 = 1, \quad \beta_1 = a, \]
hence \( \beta_i = b^iU_i(a/2b) \) and the conclusion follows. \( \square \)

### 4. Inverse of a tridiagonal 2-Toeplitz matrix

In this section we will determine the explicit inverse of a matrix of type (1). By Theorem 2.1, this is equivalent to determine \( \delta_i \) and \( d_i \), i.e., by (7) and transformations (5) and (6), \( \theta_i \) and \( \phi_i \). So, to evaluate \( \theta_i \), we have
\[
\begin{align*}
\theta_0 &= 1, \quad \theta_1 = a, \\
\theta_{2i} &= a_2\theta_{2i-1} - b_1c_1\theta_{2i-2}, \\
\theta_{2i+1} &= a_1\theta_{2i} - b_2c_2\theta_{2i-1}.
\end{align*}
\]
Making the change
\[ z_i = (-1)^i\theta_i, \]
we get the relations
\[
\begin{align*}
z_0 &= 1, \quad z_1 = -a, \\
z_{2i} &= -a_2z_{2i-1} - b_1c_1z_{2i-2}, \\
z_{2i+1} &= -a_1z_{2i} - b_2c_2z_{2i-1}.
\end{align*}
\]
According to the results in [6],
\[ z_i = Q_i(0), \]
where \( Q_i \) is a polynomial of degree exactly \( i \), defined by the recurrence relation
\[ Q_{i+1}(x) = (x - \tilde{\beta}_i)Q_i(x) - \tilde{\gamma}_iQ_{i-1}(x), \]
where
\[
\begin{align*}
\tilde{\beta}_{2j} &= a_1, \\
\tilde{\beta}_{2j+1} &= a_2, \\
\tilde{\gamma}_{2j} &= b_2c_2, \\
\tilde{\gamma}_{2j+1} &= b_1c_1,
\end{align*}
\]
and initial conditions \( Q_0(x) = 1 \) and \( Q_1(x) = x - \tilde{\beta}_0 \).
The solution of the recurrence relation (8) with coefficients (9) is
\[ Q_{2i}(x) = P_i[\pi_2(x)], \quad Q_{2i+1}(x) = (x - a_1)P_i^2[\pi_2(x)], \quad (10) \]
where
\[ \pi_2(x) = (x - a_1)(x - a_2), \quad (11) \]
\[ P_i^2(x) = (b_1b_2c_1c_2)^i U_i \left( \frac{x - b_1c_1 - b_2c_2}{2 \sqrt{b_1b_2c_1c_2}} \right), \quad (12) \]
and
\[ P_i(x) = (b_1b_2c_1c_2)^i \left[ U_i \left( \frac{x - b_1c_1 - b_2c_2}{2 \sqrt{b_1b_2c_1c_2}} \right) ight] + \beta U_{i-1} \left( \frac{x - b_1c_1 - b_2c_2}{2 \sqrt{b_1b_2c_1c_2}} \right), \quad (13) \]
with \( \beta^2 = b_2c_2/b_1c_1 \). We may conclude that
\[ \theta_i = (-1)^i Q_i(0). \]
Now, to evaluate \( \phi_i \) we put
\[ \psi_i = \phi_{n+1-i}, \]
for \( i = 1, \ldots, n \), and we have to distinguish the cases when the order \( n \) of the matrix (1) is odd and when it is even.

First let us suppose that \( n \) is odd. Then we have
\[ \psi_0 = 1, \quad \psi_1 = a_1, \]
\[ \psi_{2i} = a_2 \psi_{2i-1} - b_2c_2 \psi_{2i-2}, \]
\[ \psi_{2i+1} = a_1 \psi_{2i} - b_1c_1 \psi_{2i-1}. \]
Following the same steps as in the previous case, we obtain
\[ \psi_i = (-1)^i Q_i(0), \]
i.e.,
\[ \phi_i = (-1)^i Q_{n+1-i}(0), \]
where \( Q_i(x) \) is the same as (10) but with \( \beta^2 = b_1c_1/b_2c_2 \) in (13). Notice that if \( b_1c_1 = b_2c_2 \), then \( \theta_i = \phi_{n+1-i} \).

If \( n \) is even, we get
\[ \psi_0 = 1, \quad \psi_1 = a_2, \]
\[ \psi_{2i} = a_1 \psi_{2i-1} - b_1c_1 \psi_{2i-2}, \]
\[ \psi_{2i+1} = a_2 \psi_{2i} - b_2c_2 \psi_{2i-1}. \]
Therefore
\[ \psi_i = (-1)^i Q_i(0). \]
i.e.,
\[ \phi_i = (-1)^{i+1} Q_{n+1-i}(0), \]
where
\[ Q_{2i}(x) = P_i[\pi_2(x)], \quad Q_{2i+1}(x) = (x - a_2) P_i^+[\pi_2(x)], \]
with \( \pi_2(x) \), \( P_i(x) \) and \( P_i^+(x) \) the same as in (11), (13) and (12), respectively. Observe that if \( a_1 = a_2 \), then \( \theta_i = \phi_{n+1-i} \).

We have determined completely the \( \theta_i \)'s and \( \phi_i \)'s of (7) – thus the inverse of the matrix – in the case of a tridiagonal 2-Toeplitz matrix (1).

**Theorem 4.1.** Let \( A \) be the tridiagonal matrix (1), with \( a_1a_2 \neq 0 \) and \( b_1 b_2 c_1 c_2 > 0 \). Put
\[ \pi_2(x) := (x - a_1)(x - a_2), \quad \beta := \sqrt{b_2 c_2 / b_1 c_1} \]
and let \( \{ Q_i(x; \alpha, \gamma) \} \) be the sequence of polynomials defined by
\[
Q_{2i}(x; \alpha, \gamma) = \left( \sqrt{b_1 b_2 c_1 c_2} \right)^i U_i \left( \frac{\pi_2(x) - b_1 c_1 - b_2 c_2}{2 \sqrt{b_1 b_2 c_1 c_2}} \right) + \gamma U_{i-1} \left( \frac{\pi_2(x) - b_1 c_1 - b_2 c_2}{2 \sqrt{b_1 b_2 c_1 c_2}} \right)
\]
\[
Q_{2i+1}(x; \alpha, \gamma) = (x - \alpha) \left( \sqrt{b_1 b_2 c_1 c_2} \right)^i U_i \left( \frac{\pi_2(x) - b_1 c_1 - b_2 c_2}{2 \sqrt{b_1 b_2 c_1 c_2}} \right),
\]
where \( \alpha \) and \( \gamma \) are some parameters. Under these conditions,
\[
(A^{-1})_{ij} = \begin{cases} 
(-1)^{i+j} b_j (j-i)/2 \ b_{k}^2 (j-i+1)/2 \ \theta_{i-1} \phi_{j+1}/\theta_0 & \text{if } i \leq j, \\
(-1)^{i+j} c_j (j-i)/2 \ c_{k}^2 (j-i+1)/2 \ \theta_{j-1} \phi_{i+1}/\theta_0 & \text{if } i > j,
\end{cases}
\]
where \( p_k = (3 - (-1)^k)/2 \), \( q_k = (3 + (-1)^k)/2 \), \([z]\) denotes the greater integer less or equal to the real number \( z \),
\[
\theta_i = (-1)^i Q_i(0; a_1, \beta),
\]
and
\[
\phi_i = \begin{cases} 
(-1)^i Q_{n+1-i}(0; a_1, 1/\beta) & \text{if } n \text{ is odd}, \\
(-1)^{i+1} Q_{n+1-i}(0; a_2, \beta) & \text{if } n \text{ is even}.
\end{cases}
\]

**Remark.** As we already noticed, under the conditions of Theorem 4.1, if \( n \) is odd and \( b_1 c_1 = b_2 c_2 \), then \( \theta_i = \phi_{n+1-i} \); and if \( n \) is even and \( a_1 = a_2 \), then also \( \theta_i = \phi_{n+1-i} \).
As a first application, let us consider a classical problem on the inverse of a tridiagonal Toeplitz matrix. Suppose that $a_1 = a_2 = a$, $b_1 = b_2 = b$ and $c_1 = c_2 = c$ in (1), with $a \neq 0$ and $bc > 0$. Therefore, we have the $n \times n$ tridiagonal Toeplitz matrix

$$
T = \begin{pmatrix}
  a & b & 0 \\
  c & a & c \\
  & c & a \\
  & & \ddots \\
  & & & c & a \\
  & & & & 0 
\end{pmatrix}.
$$

According to (14),

$$(T^{-1})_{ij} = \begin{cases} (-1)^{i+j} b^{j-i} \theta_{i-1} / \theta_n & \text{if } i \leq j, \\
(-1)^{i+j} c^{i-j} \theta_{j-1} / \theta_n & \text{if } i > j. \end{cases}$$

It is well-known and we can easily check using elementary trigonometry that

$$U_{2i+1}(x) = 2x U_i \left(2x^2 - 1\right).$$

Since $\beta = 1$ and

$$U_i \left(\frac{a^2 - 2bc}{2bc}\right) = U_i \left(2 \left(\frac{a}{2\sqrt{bc}}\right)^2 - 1\right) = \frac{\sqrt{bc}}{a} U_{2i+1} \left(\frac{a}{2\sqrt{bc}}\right),$$

from (15) we get

$$\theta_i = \left(\frac{\sqrt{bc}}{a}\right)^i U_i \left(\frac{a}{2\sqrt{bc}}\right),$$

and taking into account the above remark the $\phi_i$’s can be computed using the $\theta_i$’s, giving

$$\phi_i = \theta_{n+1-i} \left(\frac{a}{2\sqrt{bc}}\right)^{n+1-i} U_{n+1-i} \left(\frac{a}{2\sqrt{bc}}\right).$$

Therefore, the next result comes immediately.

**Corollary 4.1.** Let $T$ be the matrix in (16) and define $d := a/2\sqrt{bc}$. The inverse is given by

$$(T^{-1})_{ij} = \begin{cases} (-1)^{i+j} b^{j-i} \left(\frac{U_{i-1}(d)U_{n-j}(d)}{U_n(d)}\right) & \text{if } i \leq j, \\
(-1)^{i+j} c^{i-j} \left(\frac{U_{j-1}(d)U_{n-i}(d)}{U_n(d)}\right) & \text{if } i > j. \end{cases}$$
This result is well-known. It can be deduced, e.g., using results in the book of Heinig and Rost [2, p. 28]. The next corollary is Theorem 3.1 of Kamps [3].

**Corollary 4.2.** Let $\Sigma$ be the $n$-square matrix

$$
\Sigma = \begin{pmatrix}
a & b & 0 \\
b & a & b \\
& b & a & \ddots \\
& & & \ddots & b \\
0 & & & & b \\
\end{pmatrix}.
$$

The inverse is given by

$$(\Sigma^{-1})_{ij} = \begin{cases}
(-1)^{i+j} \frac{1}{b} \frac{U_{i-1}(a/2b)U_{n-j}(a/2b)}{U_n(a/2b)} & \text{if } i \leq j, \\
(-1)^{i+j} \frac{1}{b} \frac{U_{j-1}(a/2b)U_{n-i}(a/2b)}{U_n(a/2b)} & \text{if } i > j.
\end{cases}$$

We consider now a second application. In [3,4], the matrices of type (17), with $a > 0$, $b = 0$ and $a > 2|b|$, arose as the covariance matrix of one-dependent random variables $Y_1, \ldots, Y_n$, with same expectation. Let us consider the least squares estimator

$$
\hat{\mu}_{\text{opt}} = \frac{1^t \Sigma^{-1} Y}{1^t \Sigma^{-1} 1},
$$

where $1 = (1, \ldots, 1)$ and $Y = (Y_1, \ldots, Y_n)^t$, which estimates the parameter $\mu$ equal to the common expectation of the $Y_i$’s, with variance

$$
V(\hat{\mu}_{\text{opt}}) = \frac{1}{1^t \Sigma^{-1} 1}.
$$

According to Kamps, the estimator $\hat{\mu}_{\text{opt}}$ is the best unbiased estimator based on $Y$. So, the sum of all the entries of the inverse of $\Sigma$, $1^t \Sigma^{-1} 1$, has an important role in the determination of this estimator and therefore in the computation of the variance $V(\hat{\mu}_{\text{opt}})$. Kamps used in [3] some sum and product formulas involving different kinds of Chebyshev polynomials. We will prove the same results in a more concise way.

**Corollary 4.3.** The sum $s_i$ of the $i$th row (or column) of $\Sigma^{-1}$, for $i = 1, \ldots, n$ is given by

$$
s_i = \frac{1 + b(\sigma_{1i} + \sigma_{1,n-i+1})}{a + 2b},
$$

where $\sigma_{ij} = (\Sigma^{-1})_{ij}$, when $i \leq j$.

**Proof.** By Corollary 4.2, for $i \leq j$,
\[
\sigma_{ij} = (-1)^{i+j} \frac{1}{b} \left( \frac{r_+^i - r_-^i}{r_+ - r_-} \right) \left( \frac{r_+^{n-j+1} - r_-^{n-j+1}}{r_+^{n+1} - r_-^{n+1}} \right),
\]

where
\[
r_\pm = \frac{a \pm \sqrt{a^2 - 4b^2}}{2b}.
\]

Thus
\[
s_i = \sum_{j=1}^{i-1} \sigma_{ji} + \sum_{j=i}^{n} \sigma_{ij}.
\]

By the sum of a geometric progression and the fact that
\[
r_+, r_- = 1,
\]
we have
\[
\sum_{j=1}^{i-1} \sigma_{ji} = \frac{b (\sigma_{1i} + \sigma_{ii})}{a + 2b} + \frac{1}{a + 2b} \left( \frac{r_+^{i+1} - r_-^{i+1}}{r_+ - r_-} \right) \left( \frac{r_+^{n-i+1} - r_-^{n-i+1}}{r_+^{n+1} - r_-^{n+1}} \right)
\]
and
\[
\sum_{j=i}^{n} \sigma_{ij} = \frac{b (\sigma_{1,n-i+1} - \sigma_{ii})}{a + 2b} - \frac{1}{a + 2b} \left( \frac{r_+^{i} - r_-^{i}}{r_+ - r_-} \right) \left( \frac{r_+^{n-i} - r_-^{n-i}}{r_+^{n+1} - r_-^{n+1}} \right).
\]

Finally
\[
\left( \frac{r_+^{i+1} - r_-^{i+1}}{r_+^{n+1} - r_-^{n+1}} \right) \left( \frac{r_+^{n-i+1} - r_-^{n-i+1}}{r_+^{n-i+1} - r_-^{n-i+1}} \right) = (r_+ - r_-) \left( \frac{r_+^{n-i} - r_-^{n-i}}{r_+^{n+1} - r_-^{n+1}} \right).
\]

The previous theorem says that \( s_i \) depends only on the first row of \( \Sigma^{-1} \). In fact (as the following result says) the sum of all entries of \( \Sigma^{-1} \) depends only on \( \sigma_{11} \) and \( \sigma_{1n} \).

Corollary 4.4.
\[
\mathbf{1}^T \Sigma^{-1} \mathbf{1} = \frac{n + 2bs_1}{a + 2b}.
\]

5. Inverse of a tridiagonal 3-Toeplitz matrix

In an analogous way of the 2-Toeplitz matrices, we may ask about the inverse of a tridiagonal 3-Toeplitz matrix. To solve this case, we have to compute \( \theta_i \) and \( \phi_i \) in (7).
For \( \theta_i \), we have

\[
\begin{align*}
\theta_0 &= 1, & \theta_1 &= a_1, \\
\theta_{3i} &= a_3 \theta_{3i-1} - b_2 c_2 \theta_{3i-2}, \\
\theta_{3i+1} &= a_1 \theta_{3i} - b_3 c_3 \theta_{3i-1}, \\
\theta_{3i+2} &= a_2 \theta_{3i+1} - b_1 c_1 \theta_{3i}.
\end{align*}
\]

Making the change

\[
zi = (-1)^i \theta_i,
\]
we get the relations

\[
\begin{align*}
z_0 &= 1, & z_1 &= -a_1, \\
z_{3i} &= -a_3 z_{3i-1} - b_2 c_2 z_{3i-2}, \\
z_{3i+1} &= -a_1 z_{3i} - b_3 c_3 z_{3i-1}, \\
z_{3i+2} &= -a_2 z_{3i+1} - b_1 c_1 z_{3i}.
\end{align*}
\]

According to the results in [7],

\[
z_i = Q_i(0),
\]
where \( Q_i \) is a polynomial of degree exactly \( i \), defined according to

\[
Q_{i+1}(x) = (x - \tilde{p}_i) Q_i(x) - \tilde{y}_i Q_{i-1}(x),
\]
where

\[
\begin{align*}
\tilde{p}_j &= a_1, & \tilde{y}_j &= b_3 c_3, \\
\tilde{p}_{j+1} &= a_2, & \tilde{y}_{j+1} &= b_1 c_1, \\
\tilde{p}_{j+2} &= a_3, & \tilde{y}_{j+2} &= b_2 c_2.
\end{align*}
\]

The solution of the recurrence relation (8) with coefficients (18) is

\[
\begin{align*}
Q_{3i}(x) &= P_i [\pi_3(x)] + b_3 c_3 (x - a_2) P_{i-1} [\pi_3(x)], \\
Q_{3i+1}(x) &= (x - a_1) P_i [\pi_3(x)] + b_1 c_1 b_3 c_3 P_{i-1} [\pi_3(x)], \\
Q_{3i+2}(x) &= [(x - a_1)(x - a_2) - b_1 c_1] P_i [\pi_3(x)],
\end{align*}
\]
where

\[
\pi_3(x) = \begin{vmatrix}
  x - a_1 & 1 & 1 \\
  b_1 c_1 & x - a_2 & 1 \\
  b_3 c_3 & b_2 c_2 & x - a_3
\end{vmatrix}
\]
and

\[
P_i(x) = \left( 2 \sqrt{b_1 b_2 b_3 c_1 c_2 c_3} \right)^i \left[ U_i \left( \frac{x - b_1 c_1 - b_2 c_2 - b_3 c_3}{2 \sqrt{b_1 b_2 b_3 c_1 c_2 c_3}} \right) \right].
\]
We may conclude that
\[ \theta_i = (-1)^i Q_i(0). \]

In order to compute the \( \phi_i \)'s, we define
\[ \psi_i = \phi_{n+1-i} \]
for \( i = 1, \ldots, n \). In this situation, we have to distinguish three cases. If \( n \equiv 0 \) (mod 3), then
\[
\begin{aligned}
\psi_0 &= 1, \quad \psi_1 = a_3, \\
\psi_{3i} &= a_1 \psi_{3i-1} - b_1 c_1 \psi_{3i-2}, \\
\psi_{3i+1} &= a_3 \psi_{3i} - b_3 c_3 \psi_{3i-1}, \\
\psi_{3i+2} &= a_2 \psi_{3i+1} - b_2 c_2 \psi_{3i}.
\end{aligned}
\]

If \( n \equiv 1 \) (mod 3), then
\[
\begin{aligned}
\psi_0 &= 1, \quad \psi_1 = a_1, \\
\psi_{3i} &= a_2 \psi_{3i-1} - b_2 c_2 \psi_{3i-2}, \\
\psi_{3i+1} &= a_1 \psi_{3i} - b_1 c_1 \psi_{3i-1}, \\
\psi_{3i+2} &= a_3 \psi_{3i+1} - b_3 c_3 \psi_{3i}.
\end{aligned}
\]

and if \( n \equiv 2 \) (mod 3), then
\[
\begin{aligned}
\psi_0 &= 1, \quad \psi_1 = a_2, \\
\psi_{3i} &= a_3 \psi_{3i-1} - b_3 c_3 \psi_{3i-2}, \\
\psi_{3i+1} &= a_2 \psi_{3i} - b_2 c_2 \psi_{3i-1}, \\
\psi_{3i+2} &= a_1 \psi_{3i+1} - b_1 c_1 \psi_{3i}.
\end{aligned}
\]

It is clear that these three recurrence relations can be solved by a similar process as for the computation of the \( \theta_i \)'s (mutatis mutandis). Following in this way, we can state the next proposition.

**Theorem 5.1.** Let \( B \) be the tridiagonal matrix (2), with \( a_1 a_2 a_3 \neq 0 \) and \( b_1 b_2 b_3 c_1 c_2 c_3 > 0 \). Let
\[
\begin{aligned}
\pi_3 \begin{pmatrix} a & b & c \\ \alpha & \beta & \gamma \end{pmatrix} : x &:= \begin{vmatrix} x-a & 1 & 1 \\ \alpha & x-b & 1 \\ \gamma & \beta & x-c \end{vmatrix}, \\
P_i \begin{pmatrix} a & b & c \\ \alpha & \beta & \gamma \end{pmatrix} : x &:= 2 \sqrt{abc} \\
\times U_i \left( \frac{1}{2 \sqrt{abc}} \right) \begin{pmatrix} a & b & c \\ \alpha & \beta & \gamma \end{pmatrix} : x - (a + b + c),
\end{aligned}
\]
\[
Q_{3i}\left(\frac{a}{\alpha} \frac{b}{\beta} \frac{c}{\gamma}; x\right) := P_i\left(\frac{a}{\alpha} \frac{b}{\beta} \frac{c}{\gamma}; x\right) + \gamma(x - b) P_{i-1}\left(\frac{a}{\alpha} \frac{b}{\beta} \frac{c}{\gamma}; x\right),
\]

\[
Q_{3i+1}\left(\frac{a}{\alpha} \frac{b}{\beta} \frac{c}{\gamma}; x\right) := (x - a) P_i\left(\frac{a}{\alpha} \frac{b}{\beta} \frac{c}{\gamma}; x\right) + \alpha \gamma P_{i-1}\left(\frac{a}{\alpha} \frac{b}{\beta} \frac{c}{\gamma}; x\right),
\]

\[
Q_{3i+2}\left(\frac{a}{\alpha} \frac{b}{\beta} \frac{c}{\gamma}; x\right) := [(x - a)(x - b) - \alpha] P_i\left(\frac{a}{\alpha} \frac{b}{\beta} \frac{c}{\gamma}; x\right),
\]

where \(a, b, c, \alpha, \beta\) and \(\gamma\) are some parameters, subject to the restriction \(\alpha \beta \gamma > 0\). Under these conditions,

\[
(B^{-1})_{ij} = \begin{cases} 
-\gamma_{i+1}\beta_i \beta_{i+1} \cdots \beta_j \theta_{j-1}/\theta_n & \text{if } i \leq j, \\
-\gamma_{j+1}\gamma_{j+1} \cdots \gamma_{i} \theta_{i-1}/\theta_n & \text{if } i > j,
\end{cases}
\]  

where

\[
\beta_{s\ell+s+1} = b_{s+1}, \quad \gamma_{s\ell+s+1} = c_{s+1} \quad (s = 0, 1, 2; \ell = 0, 1, 2, \ldots),
\]

and the \(\theta_i\)'s and \(\phi_i\)'s are explicitly given by

\[
\theta_i = (-1)^i Q_i\left(\frac{a_1}{b_1c_1} \frac{a_2}{b_2c_2} \frac{a_3}{b_3c_3}; 0\right) 
\]

and

\[
\phi_i = \begin{cases} 
(-1)^{n+1-i} Q_{n+1-i}\left(\frac{a_1}{b_1c_1} \frac{a_2}{b_2c_2} \frac{a_3}{b_3c_3}; 0\right) & \text{if } n \equiv 0, \text{ (mod } 3), \\
(-1)^{n+1-i} Q_{n+1-i}\left(\frac{a_3}{b_2c_2} \frac{a_1}{b_1c_1} \frac{a_2}{b_3c_3}; 0\right) & \text{if } n \equiv 1, \text{ (mod } 3), \\
(-1)^{n+1-i} Q_{n+1-i}\left(\frac{a_2}{b_1c_1} \frac{a_3}{b_3c_3} \frac{a_1}{b_2c_2}; 0\right) & \text{if } n \equiv 2, \text{ (mod } 3).
\end{cases}
\]

Acknowledgments

This work was supported by CMUC (Centro de Matemática da Universidade de Coimbra). The authors thank the editor as well as the unknown referees for their helpful remarks which helped to improve the final version of the paper.
References